



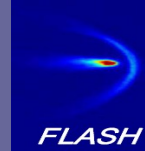
ATCA-based LLRF System for XFEL

Demonstration at FLASH

Waldemar Koprek, DESY
for the XFEL LLRF team



- Introduction to ATCA
- LLRF System for the European XFEL
- ATCA-based LLRF System
- Demonstration at FLASH



XFEL
X-Ray Free-Electron Laser

ATCA Standard and xTCA for Physics



ATCA Standard



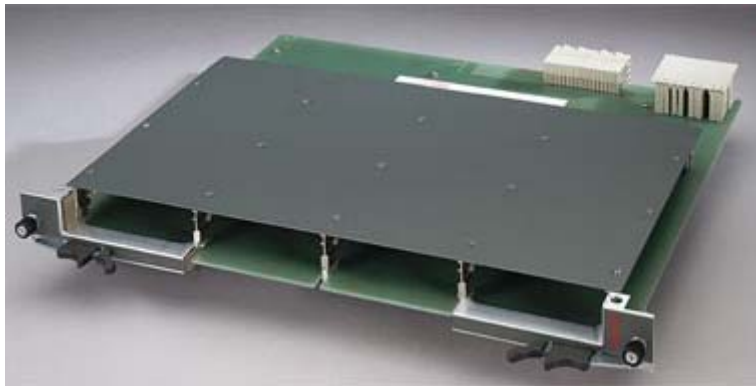
Open Modular
Computing Specifications

Advanced TCA[®]
Advanced MC[™]

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PICMG 3.0 – Advanced Telecommunications Computer Architecture

PICMG AMC.0 – Advanced Mezzanine Card





PICMG xTCA for Physics Coordinating Committee

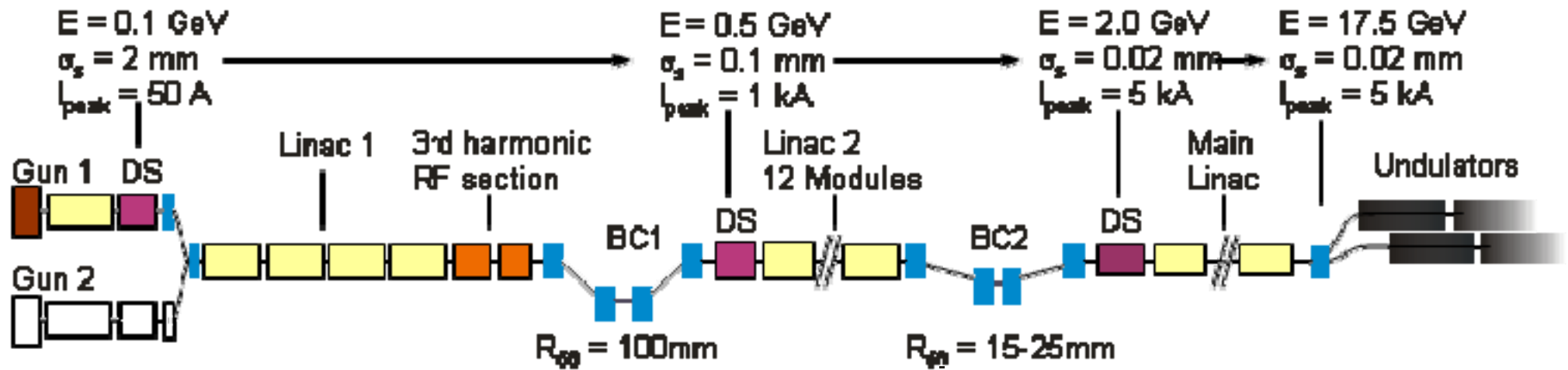
- xTCA for physics objectives:
 - Extensions to specifications
 - Guidelines
 - Open source solutions
 - Approval by PICMG membership vote
 - Collaborate with industry for vendor support
 - Building on existing xTCA base under PICMG rules

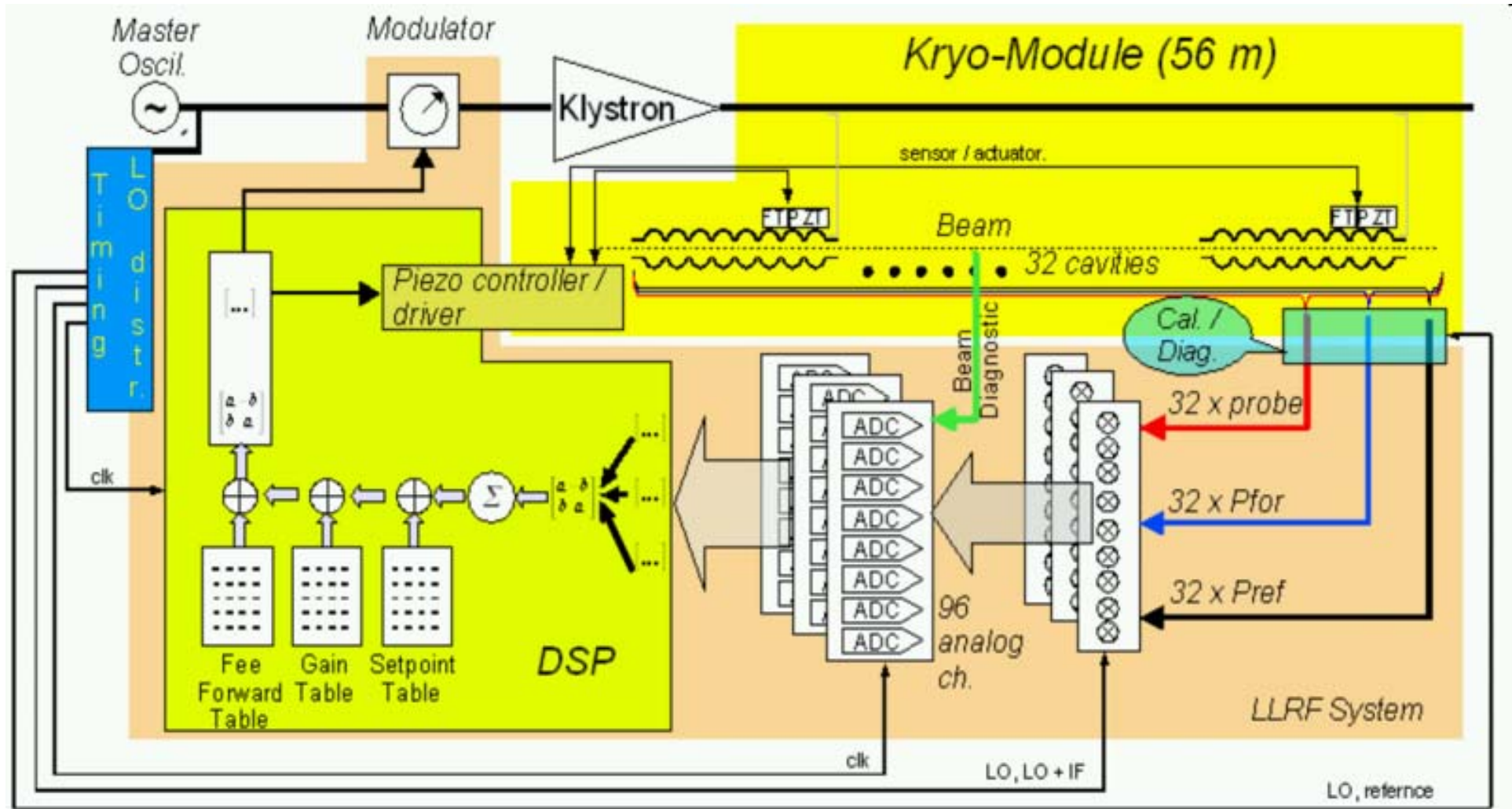
http://www.picmg.org/pdf/PICMG_Physics_Public_Web_Update_061209_R5-3.pdf





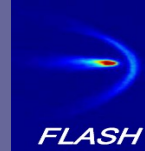
ATCA Design for LLRF





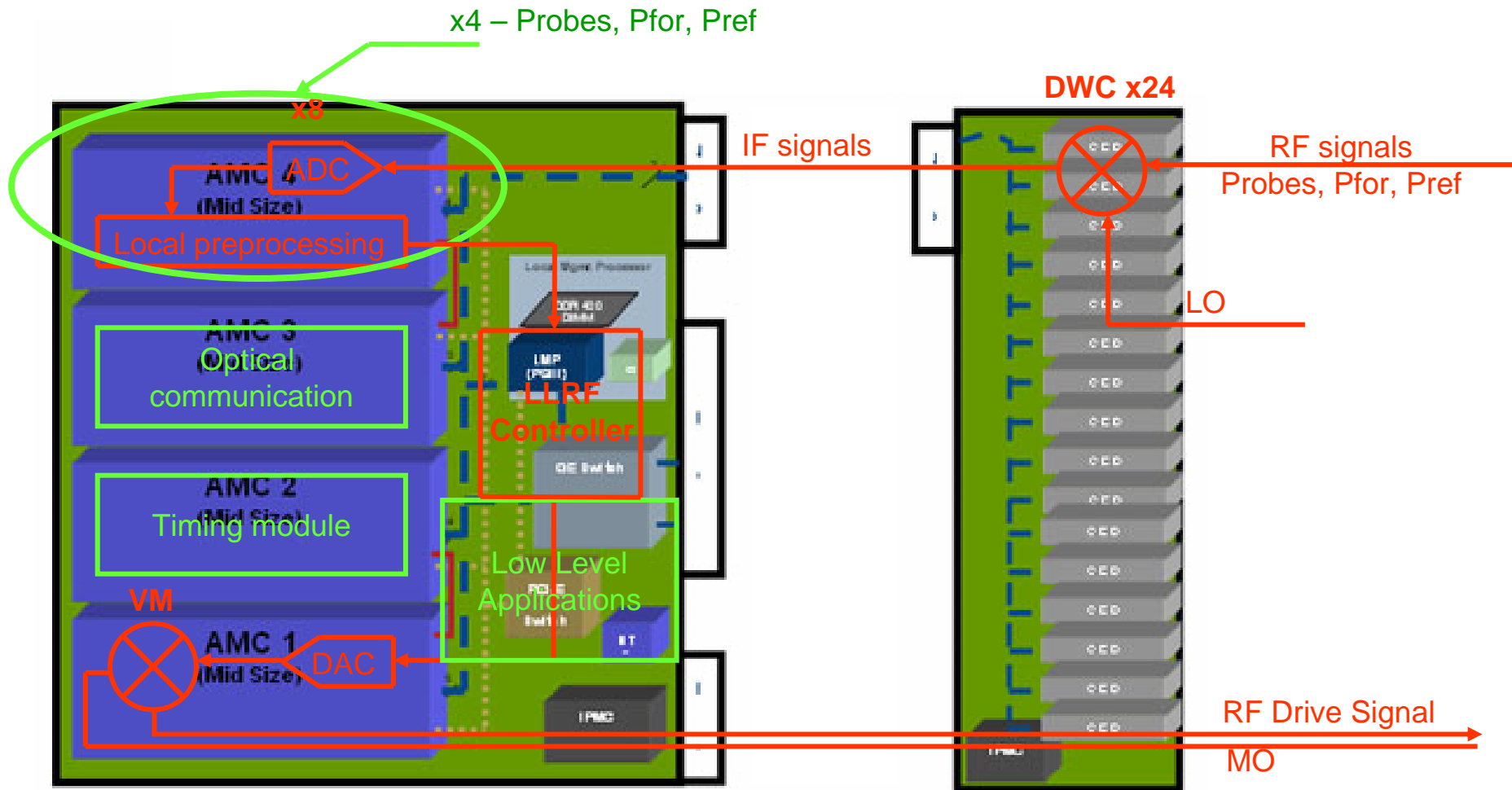


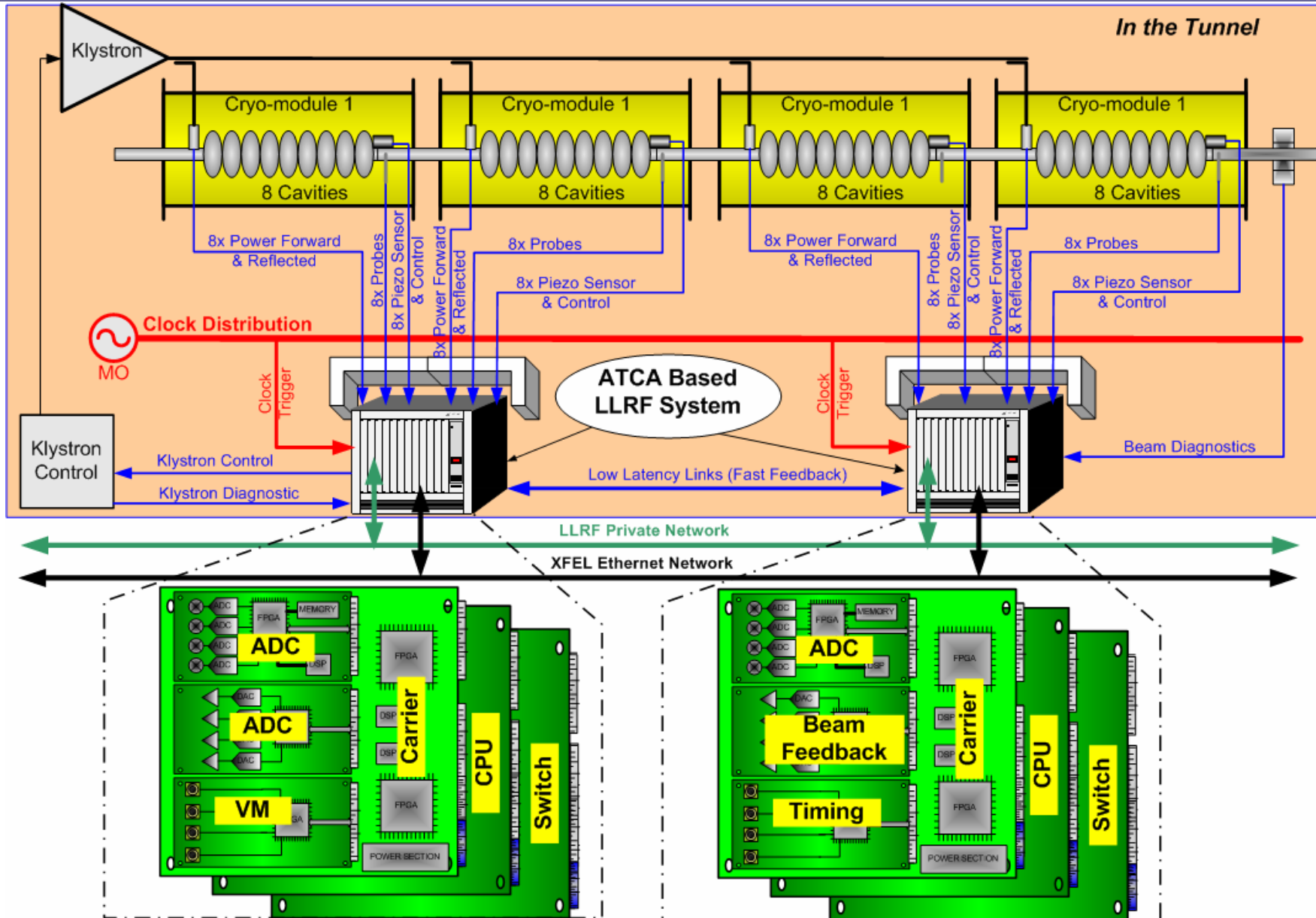
Decision for ATCA

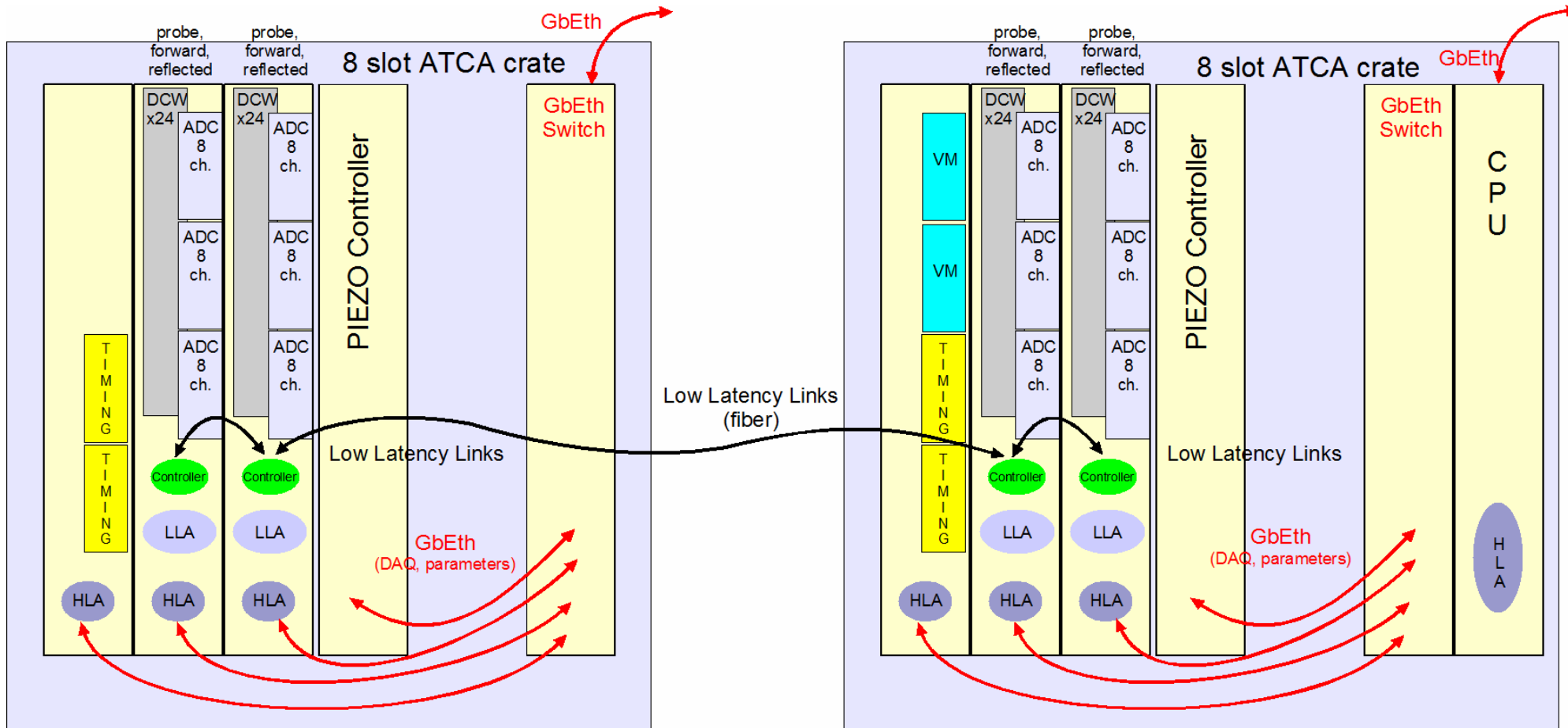


XFEL
X-Ray Free-Electron Laser

- Future LLRF systems will require simultaneous data acquisition of up to **100 fast ADC channels** at sampling rates of around **100 MHz** and real time signal processing within a few **hundred nanoseconds**.
- Also desirable are **modularity and scalability** of the design as well as **compatibility** with accelerator instrumentation needs including the control system.
- All these requirements can be **fulfilled with the new telecommunication standard ATCA**

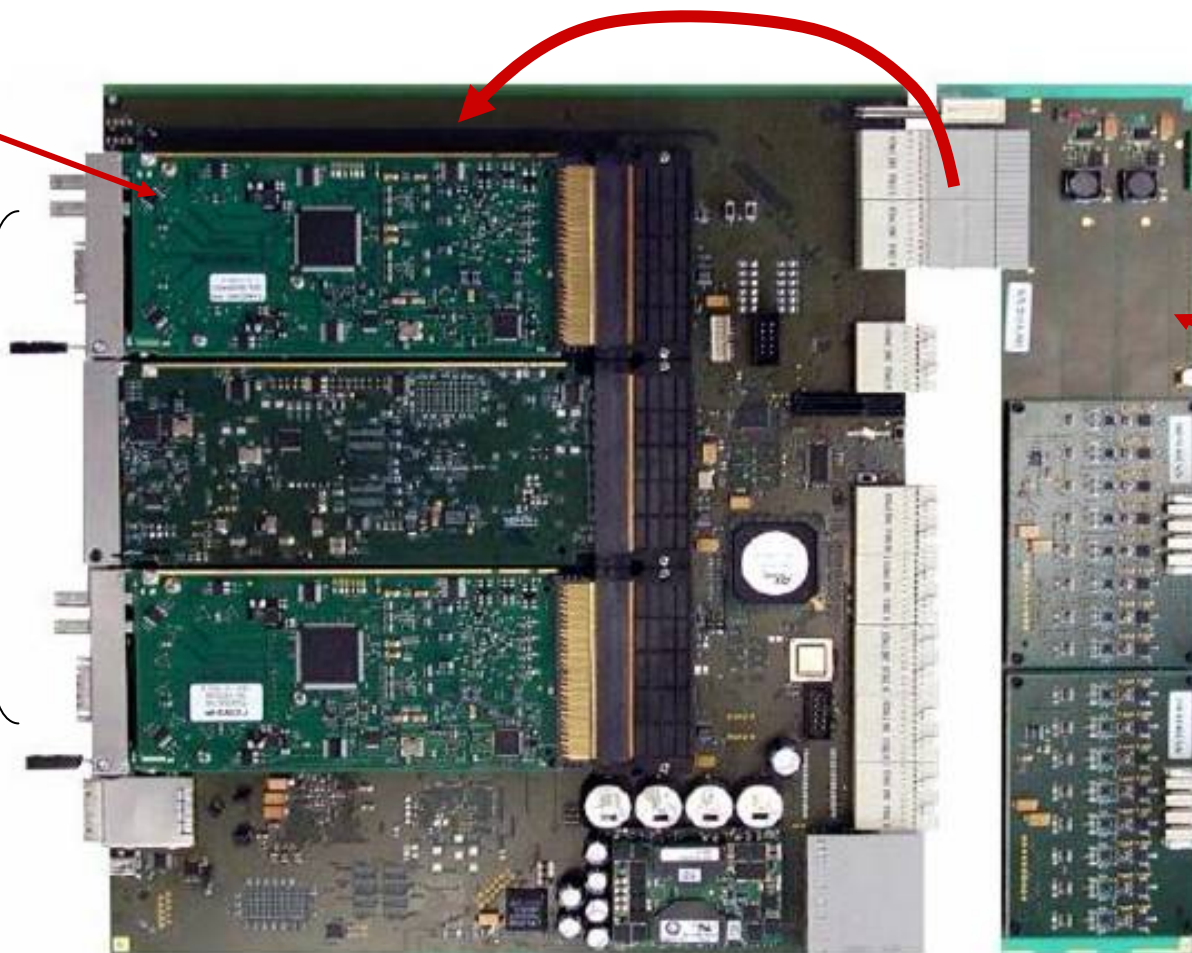






Stacked 1-wide
AMC ADC's &
IO AMC's,
connectors

105 MHz
14 bit 8 Ch
COTS ADC's

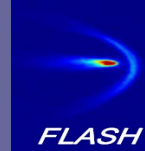


RTM

Down-converters
To 25 MHz IF

1.3 GHz
RF Inputs

TUWG105, Dariusz Makowski – “ATCA Carrier Board for LLRF System of XFEL Accelerator”



XFEL
X-Ray Free-Electron Laser

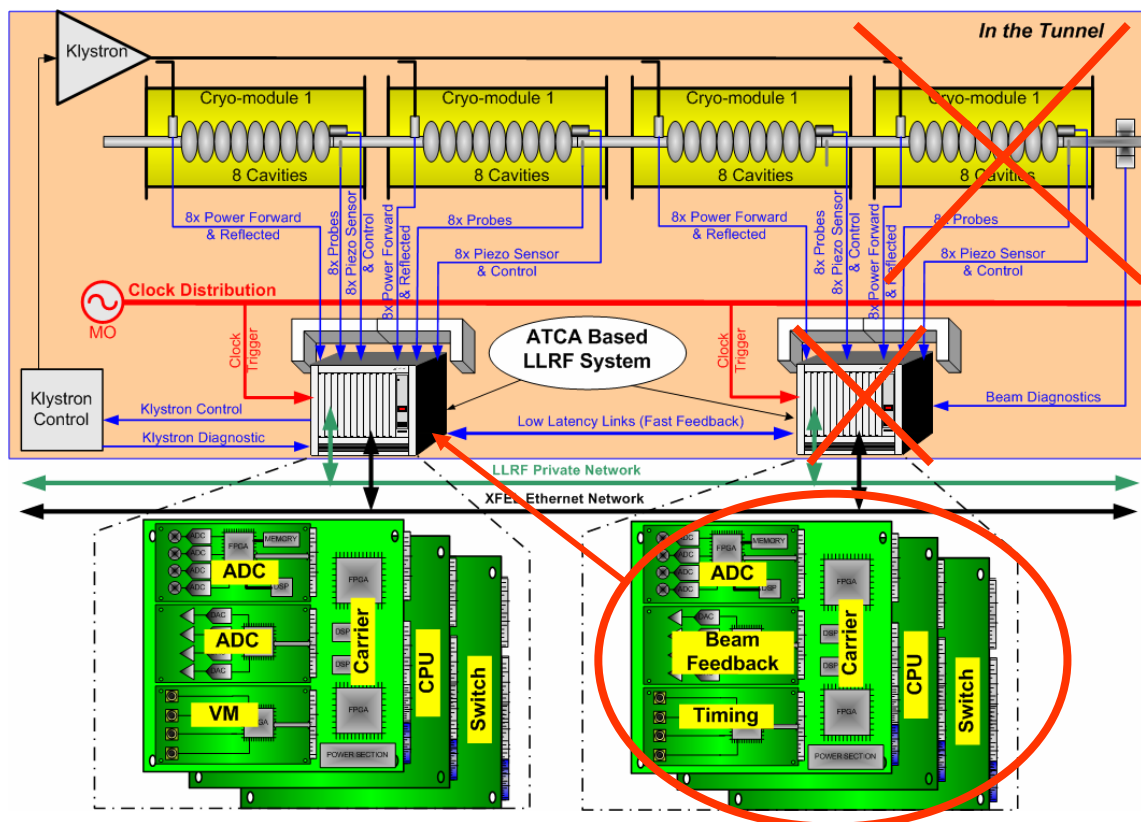
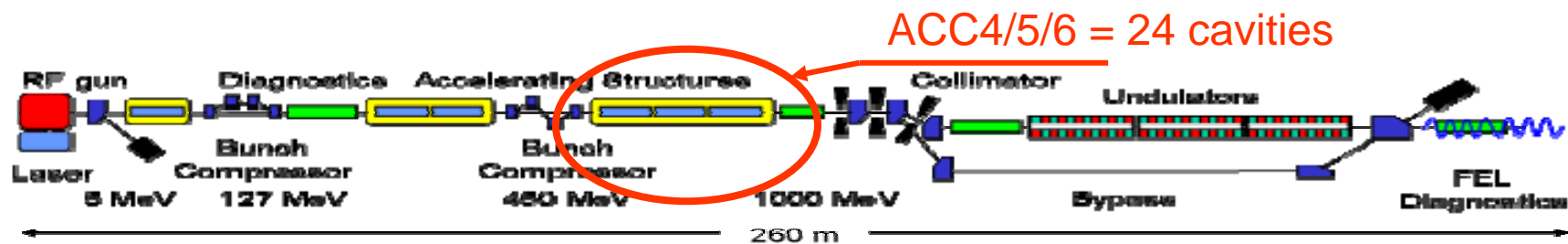
ATCA Demonstration at FLASH

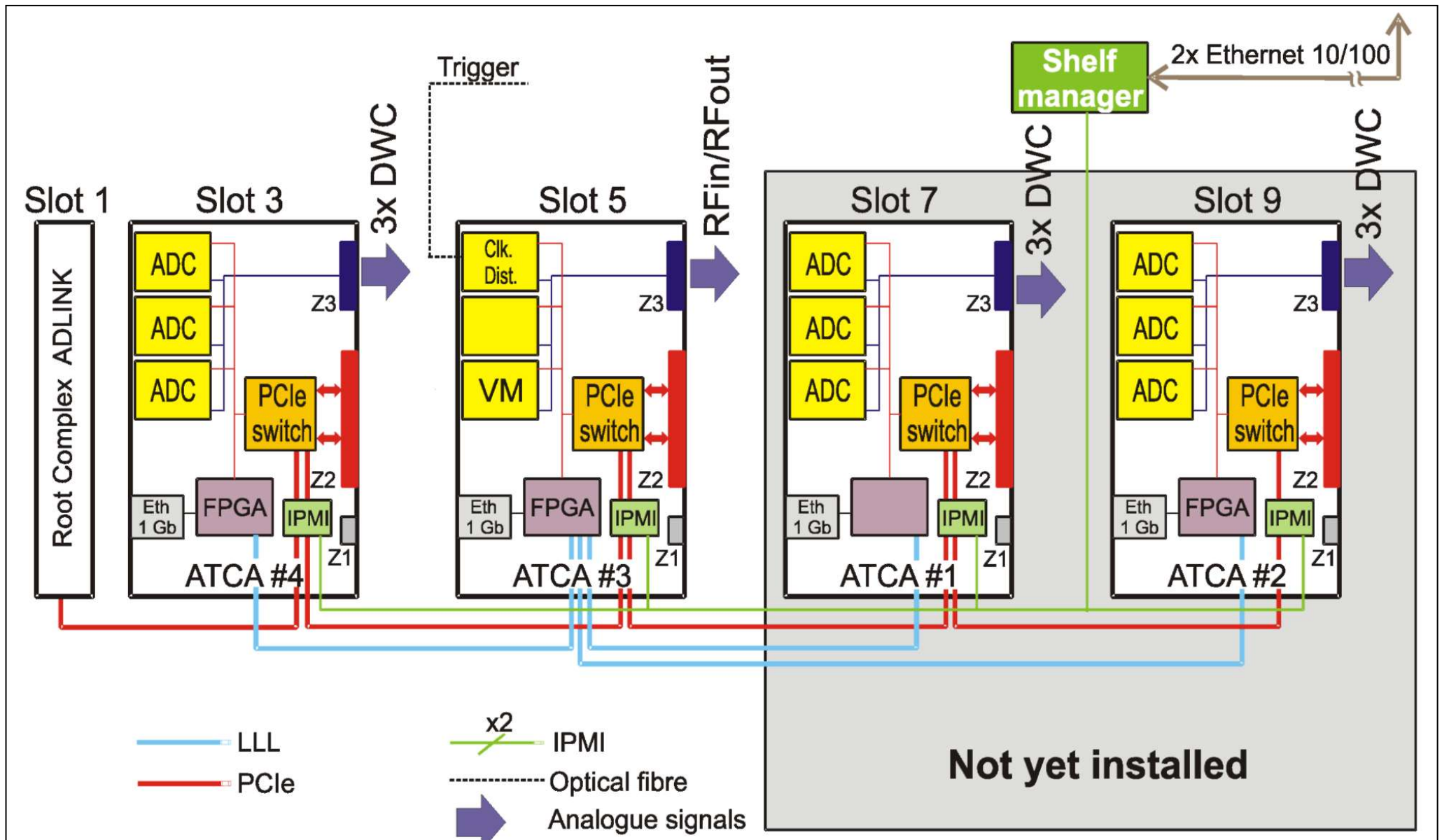


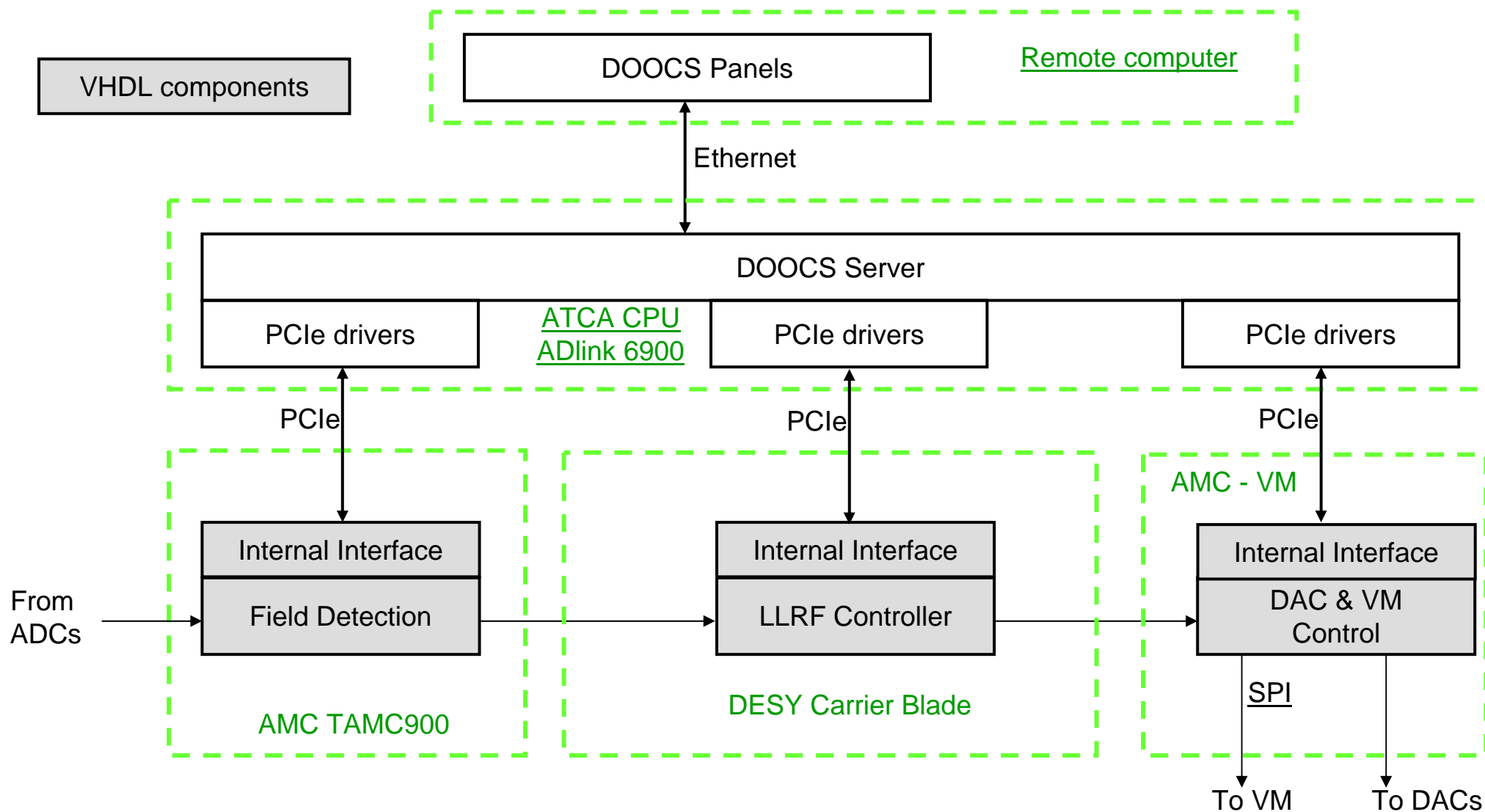
Demonstration Goals



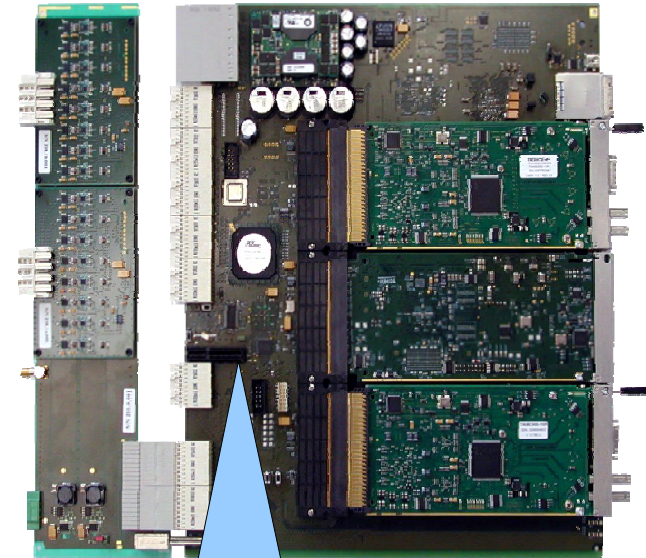
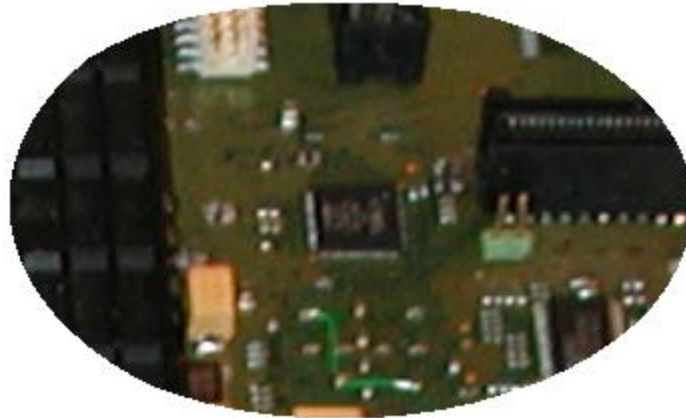
| Objective | Comment |
|--------------------------------------|--|
| Analog IO | Demonstrate the noise added from entrance to rear transition module through Zone 3 and carrier to AMC module is not degraded |
| Communication links | Demonstrate that the scheme of Low Latency Links, PCIe and GbE is functional. |
| Operation in accelerator environment | Demonstrate that the ATCA based LLRF is functional in the noisy accelerator environment. |
| Rear transition module | Demonstrate the concept of rear transition modules with downconverters |
| Timing distribution | Demonstrate timing distribution functionality |
| Timing jitter | Demonstrate that the measured timing jitter is adequate for LLRF control. |
| IPMI | Demonstrate the IPMI implementation. |





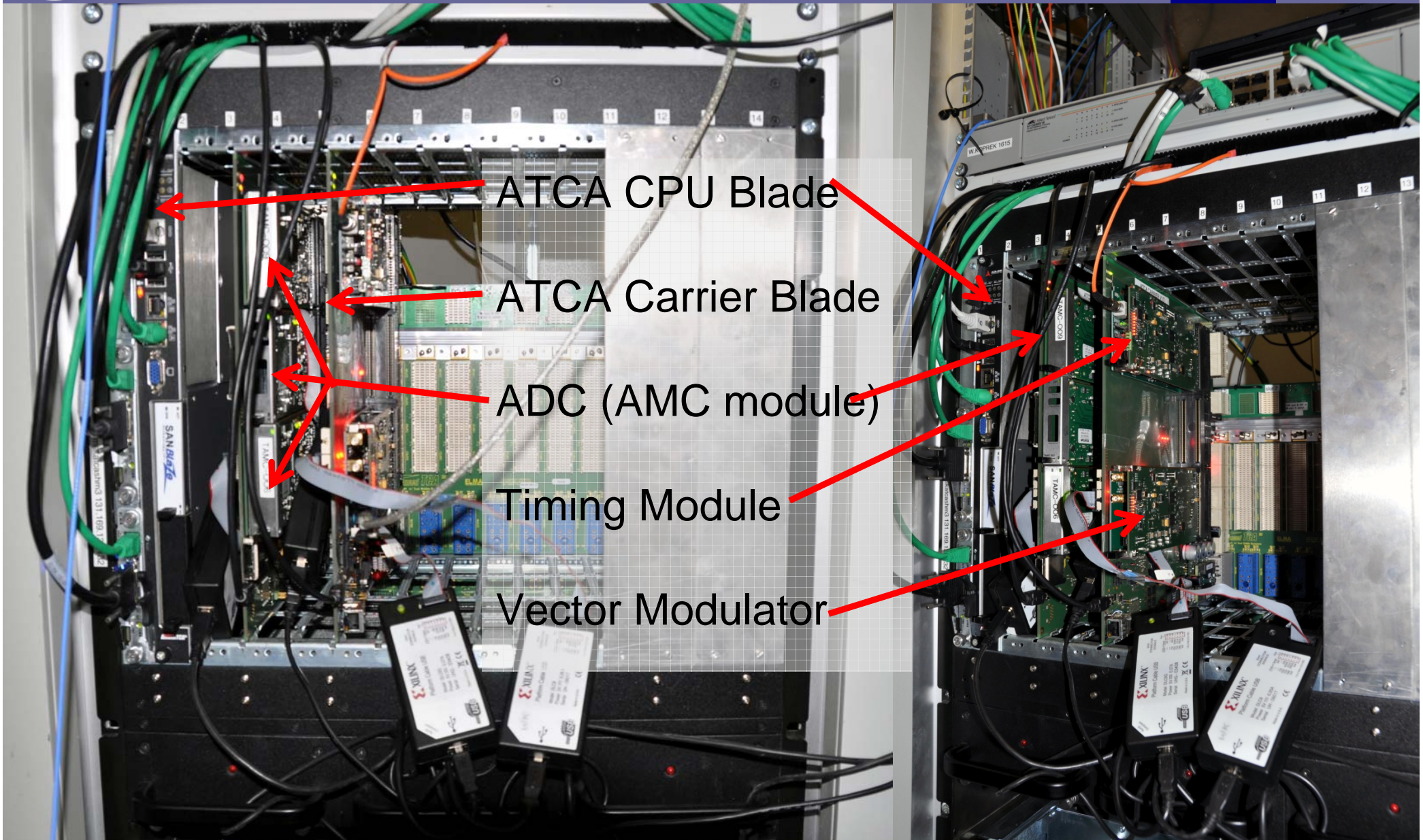


TP26, Wojciech Jalmuzna – “Development of Functional Modules for LLRF Field Controller”



- Management of ATCA carrier blades,
- Management of AMC modules,
- Monitoring of ATCA health (diagnostics),
- E-Keying for PCIe, Gb Ethernet and user defined Low Latency Connection,
- Monitoring of temperature, power supply, clocks, etc...

IPMC
ATMEGA 1281
microcontroller with
dedicated
management hardware





Set-up in Lab with 4 Carrier Blades



ATCA Expert Control Panel ACC456

SET POINT

Gradient
+ 4.35 MV/m

Phase
+ 0.00 deg

Phase offset rel. to beam
+ 0.00 deg

OPERATION

FeedForward

FeedBack

Ratio + 0.60

Gain + 50.00

OUTPUT

Offset I + 15810

Offset Q + 500

TABLES **OUT I&Q**

ERR I&Q **VSUM I&Q**

Klystron 4

Interlock

TIMING

Filling + 500.00 us

Flattop + 400.00 us

INPUT CALIB. ACC4

INPUT CALIB. ACC5

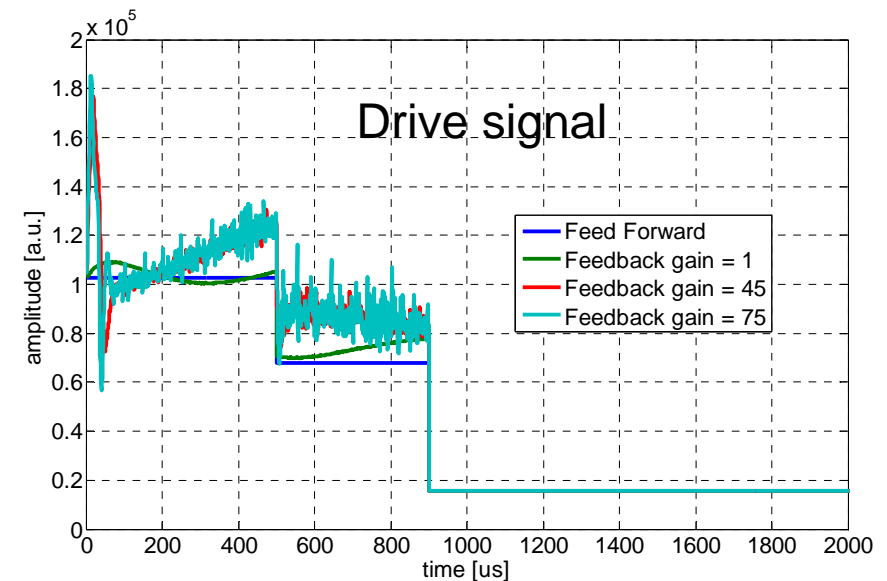
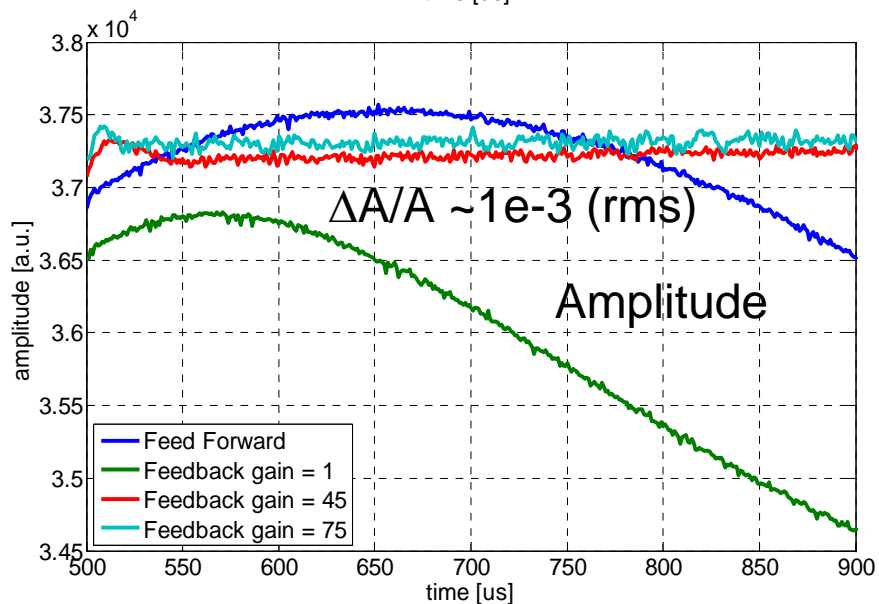
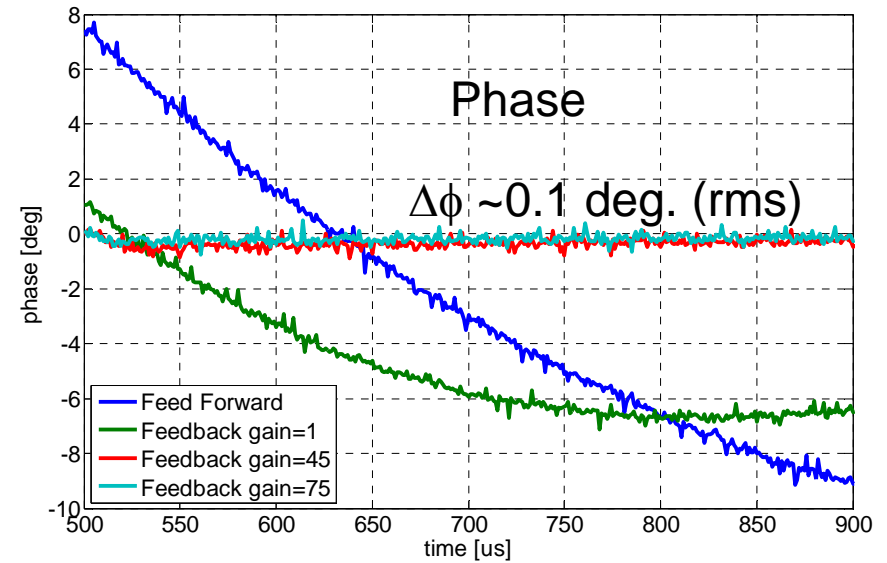
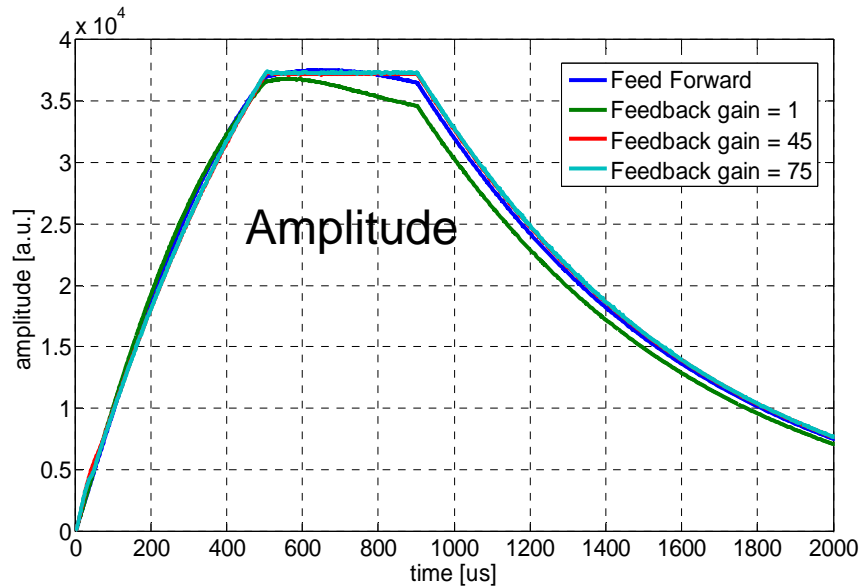
INPUT CALIB. ACC6

VM

| ACC4 | | | ACC5 | | | ACC6 | | |
|-----------|-------|----|-----------|-------|----|-----------|--------|----|
| Pfor_C1 | 43.95 | kW | Pfor_C2 | 37.23 | kW | Pfor_C1 | 112.30 | kW |
| Ptrans_C1 | 0.88 | W | Ptrans_C2 | 0.49 | W | Ptrans_C1 | 1.48 | W |

Top Plot: Signal vs Time (0 to 1000). Y-axis: 0 to 4e+04. Res= 1, Buf= 0.

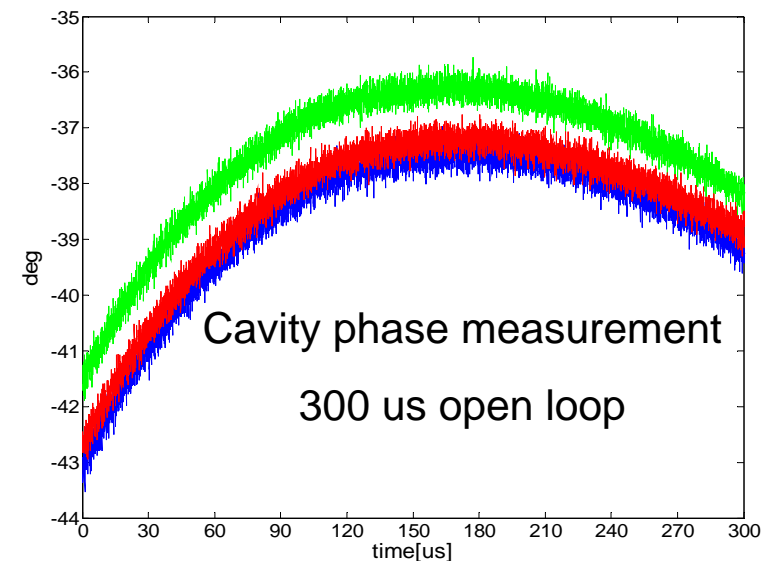
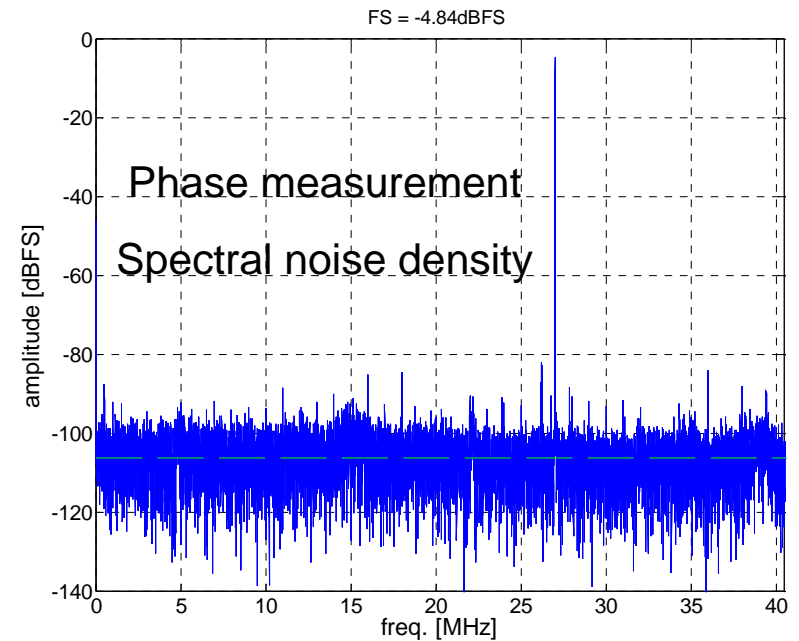
Bottom Plot: Signal vs Time (0 to 1000). Y-axis: -25 to 25. Res= 1, Buf= 0.



Preliminary Performance Data

- Channel isolation >80 dB @50MHz (presently limited by downconverter)
- Noise < 200 μ V (rms) consistent with 14-bit ADC, 200 MHz bandwidth
- Timing jitter < 15 ps (rms) @ 81 MHz (upper limit, could be dominated by RF)

| | ADC1 | ADC2 | ADC3 | ADC4 | ADC5 | ADC6 | ADC7 | ADC8 |
|---------|--------|--------|--------|--------|--------|--------|--------|--------|
| ADC1 on | -67.87 | -48.14 | -66.86 | -66.39 | -73.71 | -69.90 | -67.11 | -71.38 |
| ADC2 on | -48.35 | -67.79 | -68.14 | -74.08 | -69.35 | -71.00 | -67.86 | -72.67 |
| ADC3 on | -59.51 | -66.47 | -68.09 | -52.43 | -66.08 | -70.39 | -66.98 | -72.60 |
| ADC4 on | -65.52 | -69.55 | -49.03 | -68.03 | -68.82 | -69.81 | -66.69 | -70.78 |
| ADC5 on | -73.27 | -73.27 | -67.81 | -69.82 | -66.44 | -44.35 | -63.30 | -69.77 |
| ADC6 on | -2.92 | -0.45 | 0.56 | -3.24 | 17.30 | -8.12 | 4.08 | 8.28 |
| ADC7 on | -76.22 | -70.18 | -69.39 | -77.31 | -65.34 | -70.27 | -68.47 | -45.76 |
| ADC8 on | -70.80 | -63.62 | -62.15 | -69.65 | -67.48 | -62.79 | -52.15 | -64.50 |





Conclusion



- The demonstration of the ATCA-based LLRF system at the FLASH user facility has verified that this standard can be employed for a wide range of **physics applications**:
 - **ATCA for large scale and high performance systems**
 - **μ TCA for low cost instrumentation needs**
 - **and combinations of these standards**
- Although standard is quite new **commercial components** and even complete systems are already available for physics applications.
 - Several physics labs are already using or evaluating the ATCA and μ TCA standard
- xTCA for physics standardization effort between labs and industry will release first specifications in 2010 and should lead to commercially available products within 1-2 years.



Project Participants



- Technical University of Lodz, DMCS, Poland
 - Wojciech Cichalewski
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 - Frank Ludwig
 - Stefan Simrock
 - Henning Weddig